

# Microwave Update

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# Summary

- Microwave Motor System
- Controls Error Checking and Position Tracking
- Automated Simulation

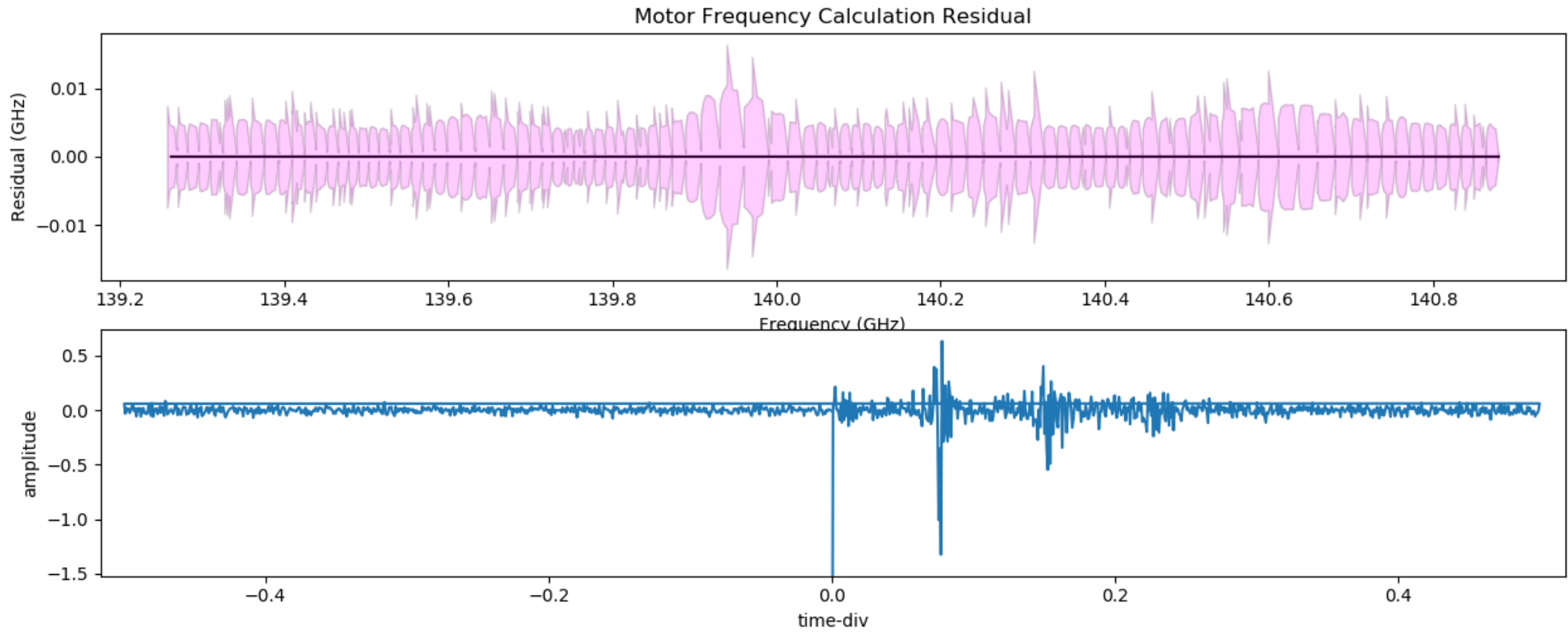
# Motor Control System

- New motor and accompanying controller ordered.
- Controller and motor are separate to alleviate radiation worries.
- New controller is directly compatible with the current controllers communications format – no need to change code.
- New system allows us to have a HOME algorithm and absolute position read-back.
- This eliminates two previous problems.

# Controls Error Checking and Position Tracking

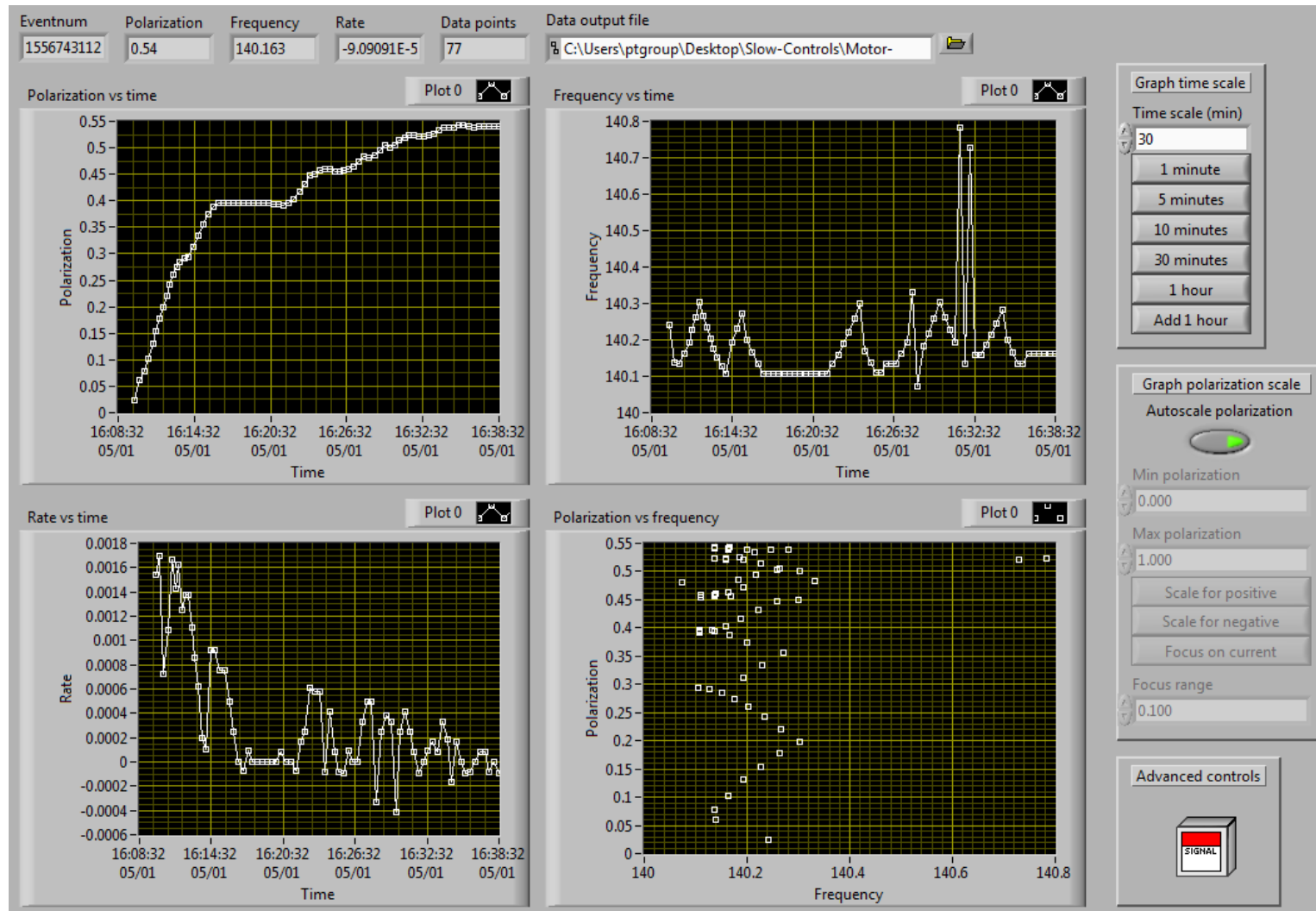
- Tests so far have shown the calculated frequency to EIP read-back frequency track to around the 5 MHz level.
- Understanding if the frequency calibration drifts with time is important.
- The read-back from both the EIP and motor controller need better error checking or possibly less resolute sampling.
- Errors cause analysis to need substantial data cleaning.

# Controls Error Checking and Position Tracking



# Automated Simulation

- Automated frequency adjustment seems to work. Needs a longer set of testing with different settings.



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